ABSTRACT
With the breakthrough of Independent Component Analysis (ICA) algorithm, it is possible now to even analyze the measured electromagnetic brain signals. Analysis with a conventional Independent Component Analysis (ICA) algorithm has previously demonstrated the results but the square mixing matrix assumption of conventional ICA causes large number of sources to be estimated. The modern ICA algorithm addresses this problem by extracting the signal sources which is closest in same sense, to a supplied reference signal. In this paper, we propose a method for delay estimation in separating speech of individual speakers from a multi-speaker speech signal using the knowledge of excitation source information. We examined and demonstrated our approach with two-microphone system for two and three dimensional signals. Through this paper, we present a technique for separating the audio sources from a single mixture. The system is based on the extraction of independent basis function from the mixture spectrogram and grouping them to produce the source subspaces. Principal component analysis is used for dimension reduction and independent component analysis is employed to make the basis functions independent from each other. The proposed algorithm is suitable for better grouping of the basis functions to separate the individual source. The satisfactory result of two-source mixture separation motivates to use our technique for real world single mixture source separation.

Keywords-Independent component Analysis, delay estimation, analysis of signals, multi-speaker speech signal, novel approach

1.INTRODUCTION
Models incorporating “latent” variables have been commonplace in the social and behavioral sciences for a long time. The most popular of those models is the factor analysis model, in which a set of observed continuous variables is explained in terms of a much smaller set of continuous latent variables (called factors), and the relationship is taken to be a linear one. Latent variables, which can be continuous or discrete, are quite different from observed variables in that they are artificial or hypothetical constructs.

Latent variables are typically used to give a formal representation of ideas or concepts that cannot be well-defined or measured directly. In educational and psychometric research, for example, fuzzy concepts such as “general intelligence,” “verbal ability,” “ambition,” “socioeconomic status,” “quality of life,” and “happiness” is constructed from certain observed variables that are regarded as proxies for those unobservable concepts. Moreover, it is not unusual to hear of a causal relationship between a latent variable and a set of given observable variables (e.g., “it is because of a person’s high level of intelligence that he or she does so well on standardized tests”). Latent variables are also known, for example, as hidden variables in neural network modeling and as sources that are statistically independent of each other in independent component analysis. Latent variables have been introduced into MCMC sampling as auxiliary variables and as a data-augmentation technique in missing-value problems. Latent variables are usually formed as linear combinations of observable variables for the purpose of reducing the dimensionality of a data set. Indeed, it is easier to consider a single latent variable interpreted as “quantitative ability” than to have to deal with understanding a battery of different arithmetic and mathematics test scores. As we will see, latent variables play the fundamental role of “sources” in blind source separation problems.
2. BLIND SOURCE SEPARATION

Used in sound and image processing, brain imaging, remote sensing, signal processing, stock-market movement. An example of Blind source separation is cocktail party problem 'm' persons are speaking in a party simultaneously 'r' microphones placed at different distances in the same room and record a different mixture of speakers voice at different time points.

The problem is to separate out speech signals of each of each of 'm' speakers based upon these microphone recordings. Thus the problem is immixing the mixture of signals. Special cases of this model include independent component analysis.

3. INDEPENDENT COMPONENT ANALYSIS (ICA)

Independent component analysis (ICA) is a multivariate statistical technique that seeks to uncover hidden variables in high-dimensional data. As such, it belongs to the class of latent variable models. Furthermore, because of its success in analyzing signal processing data, ICA is also regarded as a digital signal transform method. In its most basic form, the ICA model is assumed to be a linear mixture of an unknown number of unknown hidden source variables, where the mixing coefficients are also unknown. A totally “blind” approach to determining both the hidden variables and the mixing coefficients solely from the observed multivariate data fails because the problem as stated is not well-defined.

To build more structure into the problem, we require the hidden variables to be mutually independent and also (with at most one exception) non-Gaussian. ICA is actually an amalgam of several related approaches to this problem, and these approaches are characterized by the types of assumptions visited upon the distributions of the independent source variables and whether or not a separate noise component should be included in the ICA model.

3.1 ICA Model

<table>
<thead>
<tr>
<th>APPLICATIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td>EEG</td>
</tr>
<tr>
<td>ERP</td>
</tr>
<tr>
<td>MEG</td>
</tr>
<tr>
<td>FMRI</td>
</tr>
</tbody>
</table>

Table 1. ICA general and medical applications

Linear mixture of unknown number of unknown variables, where mixing coefficients are also unknown, hidden variables are assumed to be non Gaussian and independent. ICA has vast no. of applications. We come across many medical applications like EEG, etc. in our life. It has made the estimation of signals particularly in medical diagnosis very efficient.

3.1 General ICA problem

In general form we assume that \( \tilde{X} \) is generated by

\[
\tilde{X} = g(\tilde{S}) + \tilde{e}
\]

Where \( \tilde{S} = S_1 \), mX1 vector of unobservable source component (latent source variables)

\( Sm \)

\( \tilde{X} = X_1 \), rX1 vector of observation

\( Xr \)

g: mixing function

\( \tilde{e} = e_1 \)

= error
er
g : RmRr
BSS problem is to invert g & find $\tilde{s}$
$S_j = j$th latent variable : assume to have mean 'zero' & variance '1'
If $g(\tilde{s})=A\tilde{s}$ where 'A' is a $r \times m$ matrix of mixing parameter then model is linear ICA model.
If $g(\tilde{s})$ is non-linear we have non-linear ICA model.
*(mixing function is unchanged with time)*
If 'e' is not included then all noise is associated with s and model is called noiseless ICA if 'e' is included, then model is called "noisy ICA".
Let us consider ICA with linear structure
\[ \tilde{X} = A\tilde{S} \]
We assumed that s is non-Gaussian and has independent components. For Gaussian case, it is not possible to estimate $A$ & $\tilde{S}$ separately.
\[ X_i = X_{i1} \]
\[ X_i \]
$X_i$ is a $1 \times m$ vector
our is to recover 'm' independent sources.
\[ S_i = S_{i1} \]
\[ S_i \]
$S_i$ is a $1 \times m$ vector
(linearly independent)
and \[ \tilde{X}_i = A\tilde{S}_i \]
$A = r \times m$
usually $m_{sr}$ & rank of $A = m$
If 's' has mean '0' and covariance matrix 'Im'.Then $\tilde{X}$ has mean vector '0' & covariance matrix $AA^\prime$
premultiplying both side of
\[ \tilde{X} = A\tilde{S} \]
By $(A^\prime A)A \tilde{X}$ we obtain
\[ (A^\prime A)A \tilde{X} = A \tilde{S}(A^\prime A) \tilde{A} \]
\[ = \tilde{S} \]
or \[ \tilde{S} = W\tilde{X} \]
where \[ w = (A^\prime A)A^\prime : \text{unmixing/separating matrix} \]
Note: if A is square matrix = $(A^\prime A)A^\prime$
\[ = A(A^\prime A) \]
\[ = A \]
Then
\[ S_k = W_k\tilde{X} \ (k=1,2,\ldots,m) \]
$W_k$ is kth row of $W$
If $\hat{w}$ is an estimate of 'w' then we can estimate $S$ by
\[ S = \hat{w}x \]

4. The FAST ICA Algorithm
1) Centre & whiten the data.
2) choose an initial vector 'w' with unit norm
\[ ||w|| = (\tilde{w}^\prime \tilde{w}) = 1 \]
$\tilde{w}$ may be chosen randomly
3) Choose $G$ to be any non-quadratic density with first & second partial derivatives 'g' & 'g''
(some choices are log cosh & exp)
Table 2. the log cosh and exponential values of $G(y)$, $g(y)$, and $g^\prime(y)$
<table>
<thead>
<tr>
<th>G(y)</th>
<th>g(y)</th>
<th>g'(y)</th>
</tr>
</thead>
<tbody>
<tr>
<td>log cosh</td>
<td>$1/\alpha \log \cosh(\alpha y)$</td>
<td>tanh($\alpha y$)</td>
</tr>
<tr>
<td>exp</td>
<td>$e^{-y^2/2}$</td>
<td>$ye^{-y^2/2}$</td>
</tr>
</tbody>
</table>
4) (Modify the weight in average form)
5) $w = ||w||$
6) Return to steps 4&5 until convergence is achieved
FAST ICA package uses two different ways for extracting components.

4.1 Deflation
The single component routine finds a new component that new component is orthogonalized with respect to all previously found compounds and then resulting component is normalized.
4.2 Parallel
The single component routine is carried out in parallel for each independent component to be extracted and then a symmetric orthogonalization is carried out and all components simultaneously.

4.3 Deflation Algorithm
1) Centre & whiten data to give X
2) Decide a no. of components 'm' to be extracted.
3) For K=1,2,......,m
   - initialize r-vector(r*1) wk with ||wk||=1
   - let wk
     (FAST ICA single compound update)
   - let wk
   - iterate wk until convergence achieved
4) Set K = K+1 if ksm returns to step 3

4.4 Parallel algorithm
1) Centre & whiten data to give X
2) decide ( no. of component)'m'.
3) Initialize r vector w1,w2,.....wm each ||wk|| = 1
4) Carry out symmetric orthogonalization.
5) For K=1,.....m
   (weights update)
6) Carry out symmetric orthogonalization for 'w'.
7) Return to step 5 until convergence is achieved.

5. EXPERIMENT
For finding out the quality of recovery of signal, we performed various experiments which are based on three parameters which are:
(1) Number of signal
(2) Number of method
(3) Number of dimensionality

Now we will take these three parameters to check which signals recovery is best and whose recovery is worst.

5.1 TWO DIMENSIONAL SIGNAL
First we generated signals of two dimensional in which we have selected height and width randomly. In two dimensional we use images to watch the figure.

The original signal which we ran on FASTICA, following things got separated
(a) original signal
(b) Mix signal
(c) Recovering signal

Now we have to find out quality of recovery of signal which is based on three parameters which are:
(1) Number of signal
(2) Number of method
(3) Number of dimensionality

Now we will take these three parameters to check which signals recovery is best and whose recovery is worst.

Suppose: we took number of signal two. To check it we took six numbers of methods. In that we find out same get very good recovery and some get bad recovery. After six numbers of methods we find out Q (sum of square root of original signal and recovery signal) of all the methods separately.

(1) Then we find out mean individually
(2) Then finally the mean of all the means is calculated.

Similarly with the method written below, we check it till the five signals. Then we find out that as we are increasing the number of signals, the mean of Q is also increasing and the standard derivation is decreasing.
5.1.1 OUTPUT OF TWO SIGNALS

<table>
<thead>
<tr>
<th>S. No</th>
<th>Original Signal</th>
<th>Recovery Signal</th>
<th>Value</th>
<th>Individual Mean</th>
<th>Std.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.</td>
<td>1</td>
<td>2 (+)</td>
<td>0.0158</td>
<td>Q=0.0093</td>
<td>0.0093</td>
</tr>
<tr>
<td>2.</td>
<td>1</td>
<td>1 (+)</td>
<td>0.0142</td>
<td>Q=0.1421</td>
<td>0.1809</td>
</tr>
<tr>
<td>3.</td>
<td>1</td>
<td>2 (-)</td>
<td>0.0011</td>
<td>Q=0.0053</td>
<td>0.0059</td>
</tr>
<tr>
<td>4.</td>
<td>1</td>
<td>2 (-)</td>
<td>0.0147</td>
<td>Q=0.0106</td>
<td>0.0054</td>
</tr>
<tr>
<td>5.</td>
<td>1</td>
<td>2 (+)</td>
<td>0.1624</td>
<td>Q=0.1260</td>
<td>0.0515</td>
</tr>
<tr>
<td>6.</td>
<td>1</td>
<td>1 (-)</td>
<td>0.0023</td>
<td>Q=0.0134</td>
<td>0.0157</td>
</tr>
</tbody>
</table>

Table 3. The statistical data obtained from output of two signals in 2-D signals

5.1.2 OUTPUT OF THREE SIGNALS

Fig2.
Matlab experimentation view of output of two signals of 2-D signal

5.1.3 OUTPUT OF FOUR SIGNALS

Fig3.
Matlab experimentation view of output of four signals of 2-D signal

<table>
<thead>
<tr>
<th>S. No</th>
<th>Original Signal</th>
<th>Recovery Signal</th>
<th>Value</th>
<th>Individual Mean</th>
<th>Std.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.</td>
<td>1</td>
<td>3 (-)</td>
<td>0.0232</td>
<td>Q=0.0914</td>
<td>0.1287</td>
</tr>
<tr>
<td>2.</td>
<td>1</td>
<td>1 (+)</td>
<td>0.0111</td>
<td>Q=0.0384</td>
<td>0.0137</td>
</tr>
<tr>
<td>3.</td>
<td>1</td>
<td>2 (+)</td>
<td>0.2399</td>
<td>Q=0.0919</td>
<td>0.0401</td>
</tr>
<tr>
<td>4.</td>
<td>1</td>
<td>3 (-)</td>
<td>0.0350</td>
<td>Q=0.0617</td>
<td>0.0859</td>
</tr>
</tbody>
</table>

Table 4.
The statistical data obtained from output of three signals in 2-D signals

<table>
<thead>
<tr>
<th>S. No</th>
<th>Original Signal</th>
<th>Recovery Signal</th>
<th>Value</th>
<th>Individual Mean</th>
<th>Std.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.</td>
<td>1</td>
<td>2 (-)</td>
<td>0.0955</td>
<td>Q=0.1259</td>
<td>0.885</td>
</tr>
<tr>
<td>2.</td>
<td>1</td>
<td>4 (-)</td>
<td>0.2032</td>
<td>Q=0.0677</td>
<td>0.0504</td>
</tr>
<tr>
<td>3.</td>
<td>1</td>
<td>3 (-)</td>
<td>0.2261</td>
<td>Q=0.0787</td>
<td>0.0927</td>
</tr>
<tr>
<td>4.</td>
<td>1</td>
<td>4 (-)</td>
<td>0.0615</td>
<td>Q=0.1410</td>
<td>0.0579</td>
</tr>
</tbody>
</table>

Table 5. The statistical data obtained from output of four signals in 2-D signals
5.2 THREE DIMENSIONAL SIGNAL
Three dimensional is similar to the two dimensional. But in this till two dimension features are clear but as we increase the number of dimensionality are not clear. Therefore, we convert three dimensional into two dimensional. We use slice to watch the figure but as we increase the number of signals so features are not clear.

5.2.1 OUTPUT FOR TWO SIGNALS

![Matlab experimentation view of output of two signals of 3-D signal](image1)

Then increase the number of signal features are not clear. Therefore we convert three dimensional into two, dimensional. To do this we take projection.

5.2.2 OUTPUT FOR TWO SIGNALS PROJECTION

![Matlab experimentation view of output of two signals of 3-D signal](image2)

5.2.3 OUTPUT OF THREE SIGNALS

![Matlab experimentation view of output of three signals of 3-D signal](image3)

Table 6. The statistical data obtained from output of two signals in 3-D signals

<table>
<thead>
<tr>
<th>S. No.</th>
<th>Original signal</th>
<th>Recovery Signal</th>
<th>Value</th>
<th>Individual Mean</th>
<th>Std.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1</td>
<td>2 (+)</td>
<td>0.0034</td>
<td>Q=0.0033</td>
<td>0.0389</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>1 (+)</td>
<td>0.0024</td>
<td>Q=0.0025</td>
<td>0.0259</td>
</tr>
<tr>
<td>3</td>
<td>1</td>
<td>2 (+)</td>
<td>0.0050</td>
<td>Q=0.0032</td>
<td>0.0026</td>
</tr>
<tr>
<td>4</td>
<td>1</td>
<td>1 (+)</td>
<td>0.0013</td>
<td>Q=0.0013</td>
<td>0.0476</td>
</tr>
</tbody>
</table>

![Matlab experimentation view of output of three signals of 3-D signal](image4)

Table 7. The statistical data obtained from output of three signals in 3-D signals

<table>
<thead>
<tr>
<th>S. No.</th>
<th>Original signal</th>
<th>Recovery Signal</th>
<th>Value</th>
<th>Individual Mean</th>
<th>Std.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1</td>
<td>1 (-)</td>
<td>0.0124</td>
<td>Q=0.0124</td>
<td>0.0371</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>2 (+)</td>
<td>0.0572</td>
<td>Q=0.0572</td>
<td>0.0680</td>
</tr>
<tr>
<td>3</td>
<td>1</td>
<td>2 (+)</td>
<td>0.0089</td>
<td>Q=0.0089</td>
<td>0.0067</td>
</tr>
<tr>
<td>4</td>
<td>1</td>
<td>3 (+)</td>
<td>0.0116</td>
<td>Q=0.0116</td>
<td>0.0229</td>
</tr>
</tbody>
</table>

![Matlab experimentation view of output of three signals of 3-D signal](image5)
5.2.4 OUTPUT FOR FOUR SIGNALS – PROJECTION

![Fig7. Matlab experimentation view of output of four signals of 3-D signal](image)

6. RESULT COMPARISON:
From our experimentation of fast ILA over two microphone system for determining the delay estimation of multiple signals in 2-D and 3-D, we infer that the following result proofs our project and tell us that our process can be set as an example for further growth in ICA related estimations. The result of all the statistical data obtained from our experimentation of 2-D and 3-D signals in given in table 9.

<table>
<thead>
<tr>
<th>S. No.</th>
<th>Original signal</th>
<th>Recovery Signal</th>
<th>Value</th>
<th>Individual Mean</th>
<th>Std.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1</td>
<td>2 (+)</td>
<td>0.0146</td>
<td>Q=0.0546</td>
<td>0.0134</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>1 (-)</td>
<td>0.0582</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3</td>
<td>3 (+)</td>
<td>0.0912</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>4</td>
<td>4 (-)</td>
<td>0.0544</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>1 (+)</td>
<td>0.0809</td>
<td>Q=0.0473</td>
<td>0.0413</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>2 (+)</td>
<td>0.0141</td>
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</tr>
<tr>
<td></td>
<td>3</td>
<td>4 (+)</td>
<td>0.0091</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>4</td>
<td>3 (-)</td>
<td>0.0852</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>1</td>
<td>1 (-)</td>
<td>0.0210</td>
<td>Q=0.0236</td>
<td>0.0069</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>2 (-)</td>
<td>0.0293</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3</td>
<td>3 (+)</td>
<td>0.0291</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>4</td>
<td>4 (-)</td>
<td>0.0151</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>1</td>
<td>2 (-)</td>
<td>0.0150</td>
<td>Q=0.0200</td>
<td>0.0424</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>3 (+)</td>
<td>0.0395</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3</td>
<td>4 (-)</td>
<td>0.1048</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>4</td>
<td>1 (-)</td>
<td>0.0149</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 8. The statistical data obtained from output of four signals in 3-D signals

<table>
<thead>
<tr>
<th>No. of Signals</th>
<th>Two Dimensional signals</th>
<th>Three Dimension signals</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Mean</td>
<td>Std. Deviation</td>
</tr>
<tr>
<td>Q2</td>
<td>0.0511</td>
<td>0.0691</td>
</tr>
<tr>
<td>Q3</td>
<td>0.0826</td>
<td>0.0459</td>
</tr>
<tr>
<td>Q4</td>
<td>0.0997</td>
<td>0.0266</td>
</tr>
</tbody>
</table>

Table 9. Comparative statistical of 2-D and 3-D signals of two-microphone system in MATLAB

7. CONCLUSION
Independent component analysis (ICA) is a multivariate statistical technique that seeks to uncover hidden variables in high-dimensional data. As shown in the project that we have used Fast ICA technique for signal separation which is of two types deflection and parallel. Further in Fast ICA, we have used deflection technique.

Signals which is being used here is Gaussian signal. As we know that in non-Gaussian signals, there is a perfect overlapping of signals which makes its separation difficult. Therefore Gaussian signal is used for signal separation.

Thus ICA is used to reduce the dimension of signal. It is a very useful technique for signal separation which makes it extremely useful in medical field.

REFERENCE
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